## Abstract

Method for manipulation identification on a sensor

The invention relates to a method for identification of 5 manipulations on an arrangement comprising a sensor (S) which emits pulses and a recording unit (RM). Particularly in the case of a tachograph (DTCO), any possibility of manipulation must be overcome. For this purpose, the invention proposes that (S) transmits real time pulses (RTS) to the 10 the sensor recording unit (RM) and, cyclically in response to first request instructions (1.0), transmits higher data signals (DS) for a measurement, and receives a number of real time pulses (RTSN) in response to second request instructions (2.0) which in time with 15 are offset respect to the first instructions (1.0). A data signal evaluation module (DSE) compares the number of real time pulses (RTSN) with the number of data signal pulses (DSN) and thus achieves a very high level of security against manipulation.

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(Figure 1)